

There is some learning to do here. It is helpful to be familiar with the s , v and a graphs for shm

Defined as restoring force $\propto -x$

$\frac{dx}{dt} = v$... (1) is gradient of displacement

$\frac{dv}{dt} = a$... (2) is gradient of velocity

$$\therefore \frac{d^2x}{dt^2} = a \dots$$

$$\omega = 2\pi f$$

$$T = \frac{1}{f}$$

Learn $a = -\omega^2 x$

which can be written

$$\text{as } \frac{d^2x}{dt^2} = -\omega^2 x$$

This is another differential equation. It has 2 possible, very similar solutions.

Which of these solutions you use depends on where you decide to start timing from --- in other words where is $t=0$.

So $t=0$ is at max displacement:

$$x = A \cos(\omega t)$$

So $t=0$ is at the midpoint - where $x=0$.

$$x = A \sin(\omega t)$$

you can easily put $\omega = 2\pi f$ in

Don't forget this eqn too...

$$v = \pm \omega \sqrt{A^2 - x^2}$$

With reference to the x, v and a graphs.

- Max displacement is A (ie the amplitude)
- Max v is ωA
- Max a is $\omega^2 A$

In all three cases you can have both negative and positive maxima

Linking to Force

We tend to think of this in terms of a spring where $F = -Kx$

As ever we know $F = ma$ so we can combine these two to get that

$$\Rightarrow ma = -kx$$

linking to the fact
that $\frac{d^2x}{dt^2} = \text{accel}$ we can...

$$m \frac{d^2x}{dt^2} = -kx \Rightarrow \frac{d^2x}{dt^2} = -\frac{kx}{m}$$

Try & get to a place where you see
 $\frac{d^2x}{dt^2}$ and think acceleration.

The OCR B syllabus models this....